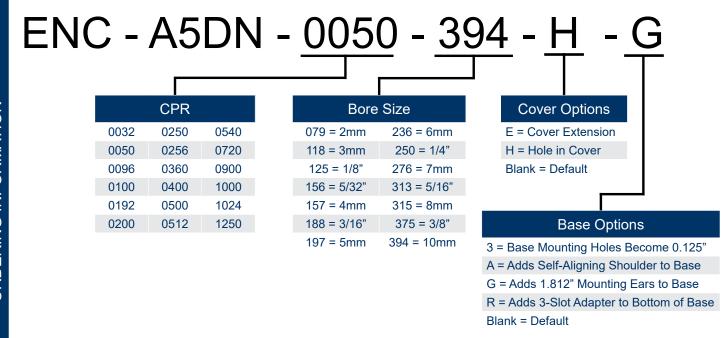




- Accepts +/- 0.010" Axial Shaft Play
- 32 to 1,250 Cycles Per Revolution (CPR)
- Tracks 0 to 300,000 Cycles Per Second
- Powered From a Single +5VDC Power Supply
- 2-Channel Quadrature Differential Squarewave Outputs
- Operating Temperature of -40° to +100° C
- RoHS Compliant and REACH Certified



ENC-A5DN is a differential encoder designed for quick and simple assembly to any shaft with a minimum length of .445" and maximum length of .570", and accepts shaft sizes ranging from .079" to .394" in diameter. The ENC-A5DN module is designed to detect the rotary position with a code wheel. When attached to the end of a shaft, the encoder provides digital feedback information. This differential encoder consists of a LED source lens and a monolithic detector IC enclosed in a small polymer package. These modules implement phase array detector technology providing superior performance and tolerances over traditional aperture mask type encoders. The ENC-A5DN series provides digital quadrature differential outputs on all resolutions and are capable of sinking or sourcing 8 mA each. These encoders are powered from a single +5VDC power supply and are RoHS compliant and REACH certified.

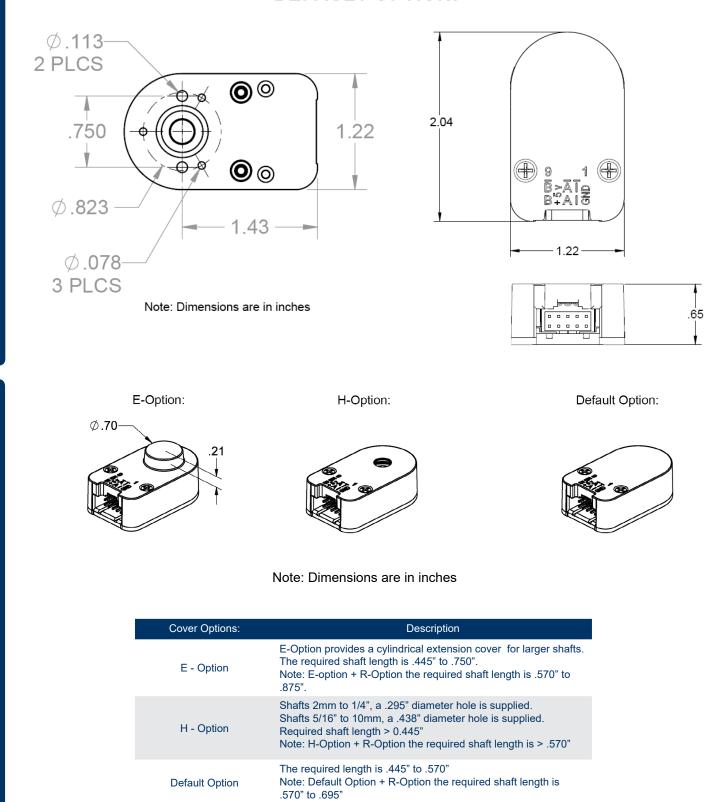


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EATURES

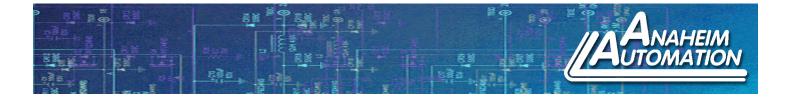


DEFAULT OPTION:



DIMENSIONS/COVER OPTIONS

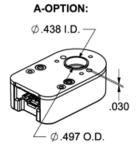
COVER OPTIONS

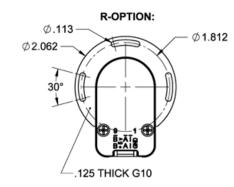


3-OPTION:

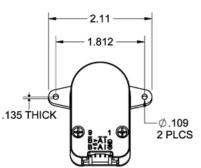


3-Option: Makes all five hole diameters .125"





G-OPTION:



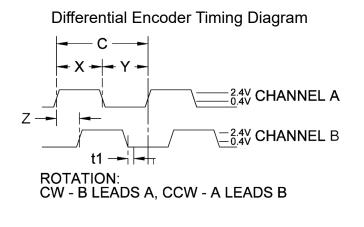
G-Option: Includes molded ears which enables it to be mounted to a 1.812" diameter bolt circle. Mounting holes are designed to fit 4-40 screws. Will work with shaft lengths of .445" to .570" and does not add to the required shaft length.

A-Option: Adds a .497" diameter alignment shoulder designed to slip into a .500" diameter recess in the mounting surface centered around the shaft. R-Option: Adapter is an 1/8" thick fiberglass adapter which is pre-mounted to the base of the encoder. It allows the encoder to rotate +/- 15 degrees. *This option adds 1/8" to the required shaft length.

Note: All dimensions are in inches

(Note: Base Mounting Screws are NOT included. #2-56 or #4-40 screws can be used to mount the base to your mounting surface.)

BASE OPTIONS



DIFFERENTIAL ENCODER PINOUT

| TOP OF EI | NCODER FACING PLUG | | |
|-----------|--------------------|--|--|
| 1. 23 | 97531 | | |
| | | | |
| Pin # | Function | | |
| 1 | Ground | | |
| 2 | Ground | | |
| 3 | No Connection | | |
| 4 | No Connection | | |
| 5 | A-Channel | | |
| 6 | A+Channel | | |
| 7 | Power | | |
| 8 | No Connection | | |
| 9 | B-Channel | | |
| 10 | B+Channel | | |
| | | | |



| Model # | Description |
|-----------------------------|---|
| CPR(N): | The Number of Cycles Per Revolution |
| One Shaft Rotation: | 360 mechanical degrees, N cycles |
| One Electrical Degree (°e): | 1/360th of one cycle |
| One Cycle (C): | 360 electrical degrees (°e). Each cycle can be decoded into 1 or 4 codes, referred to as X1 or X4 resolution multiplication |
| Symmetry: | A measure of the relationship between (X) and (Y) in electrical degrees, nominally 180 $^\circ e$ |
| Quadrature (Z): | The phase lag or lead between channels A and B in electrical degrees, nominally 90 °e |
| Index (CH I): | The Index Output goes high once per revolution, coincident with the low states of channels A and B, nominally 1/4 of one cycle (90°e) |

| Timing Characteristics | Symbol | Min | Тур | Max | Units |
|--------------------------------------|--------|-----|-----|-----|-------|
| Cycle Error | С | - | 3.0 | 5.5 | °e |
| Symmetry | X,Y | 150 | 180 | 210 | °e |
| Quadrature | Z | 60 | 90 | 120 | °e |
| Index Pulse Width | Po | 60 | 90 | 120 | °e |
| Ch. I Rise After Ch. B or Ch. A Fall | t1 | 10 | 100 | 250 | ns |
| Ch. I Fall After Ch. B or Ch. A Rise | t2 | 70 | 150 | 300 | ns |

| Parameter | Max | Units |
|-------------------------------------|----------|----------------------|
| Vibration (5 to 2kHz) | 20 | g |
| Shaft Axial Play | +/- 0.01 | in. |
| Shaft Eccentricity Plus Radial Play | 0.004 | in. |
| Acceleration | 250,000 | rad/sec ² |

| Parameter | Min | Тур | Max | Units |
|---|--------|----------------|----------------|-------|
| Supply Voltage | 4.5 | 5.0 | 5.5 | Volts |
| Supply Current CPR < 500, no load CPR \ge 500 and < 2000, no load CPR \ge 2000 | - - | 29 57 73 | 36 65 88 | mA |
| Output Low (I _{OL} = 8mA max) | - | 0.2 | 0.4 | Volts |
| Output High* I _{OL} = -8mA max | 2.4 | 3.4 | - | Volts |
| Differential Output Rise/ Fall Time | - | - | 15 | nS |

* Unloaded high level output voltage is 4.80V typically, 4.2V minimum.

| Recommended Operating Conditions | Min | Max | Units |
|-------------------------------------|-----|-----|-------|
| Temperature (CPR < 2000) | -40 | 100 | °C |
| Temperature (CPR ≥ 2000) | -25 | 100 | °C |
| Load Capacitance | - | 100 | pF |
| Count Frequency (CPR ≤ 1250) | - | 300 | kHz |
| Count Frequency (CPR 2000-2500) | - | 360 | kHz |
| Count Frequency (CPR 4000+) | - | 720 | kHz |

| Speed Cal | Units | |
|-----------------------|----------------------------|-----|
| CPR < 2000 | 18x10 ⁶ / CPR | RPM |
| CPR ≥ 2000 and < 4000 | 21.6x10 ⁶ / CPR | RPM |
| CPR ≥ 4000 | 43.2x10 ⁶ / CPR | RPM |

*60,000 RPM is the maximum RPM due to mechanical limitations.

Cables:

The following cables are compatible with Anaheim Automation's A5DN series encoder. Select a cable length from the table below:

| Cable Part Number | Length |
|-------------------|--------|
| ENC-CBL-AA4707 | 1 ft. |
| ENC-CBL-AA4707-5 | 5 ft. |
| ENC-CBL-AA4707-10 | 10 ft. |
| ENC-CBL-AA4707-20 | 20 ft. |

NOTE: For pricing and other information on cables and centering tools, please visit Accessories on our website.

Centering Tools:

Centering tools are optional, but recommended for a more precise installation.

ENC-CTOOL - 250

| Bore Size | | |
|-----------|-----------|--|
| 079=2mm | 236=6mm | |
| 118=3mm | 250=1/4" | |
| 125=1/8" | 276=7mm | |
| 157=4mm | 313=5/15" | |
| 188=3/16" | 375=3/8" | |
| 197=5mm | 394=10mm | |

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